
Fix Generator V1 1 Samsung

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1. grant of license. samsung hereby grants to you (the developer) a limited, non-exclusive, non-transferable license to use, copy, modify, merge, disassemble, distribute, and sublicense the samsung tv app sdk. first, the generator encoder is based on the same architecture as the discriminator which we call encoder-decoder architecture. the encoder is based on the spatial convolutions which allows to pass the information of the training images through layers of the generator. as convolutions are mainly performed on local spatial regions and the spatial information is already provided by the discriminator, there is no need for any additional spatial information. to achieve this we use a network based on the variational autoencoders[7] where each layer (except the last one) is a convolutional layer followed by batch normalization and relu activation function. this is one of the layers, the convolutional filters can apply. the last layer is a linear layer, which allows to output a synthesized sample from the generated distribution. the discriminator is based on the same architecture as the encoder. however, this time we are using patchgan [5] discriminator architecture which is also based on spatial convolutions. the discriminator is based on the same network architecture as the encoder, but the last linear layer is fully connected and the generator output is a mixture of three different gaussian distributions. these distributions are outputs of the linear layers, which can be interpreted as a latent space

with three different dimensions: the first dimension corresponds to real image, the second dimension corresponds to generated image, and the third dimension is for controlling the spread of the generated image. the generator is trained to maximize the log-likelihood on the training set, while the discriminator is trained to maximize the log-likelihood on the training set.

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the generator does not have the encoder stage. this means that the generator can extract the information from the training images directly. we do not have any spatial layers. the generator consists of the linear layers that provide the gaussian outputs which could be interpreted as the latent space and the gan loss layer. this means that the latent space is an additional dimension, which is used

to control the extent of the output of the synthesized sample. the generator is trained to maximize the log-likelihood of the training samples. the discriminator is trained to maximize the log-likelihood of the training samples and at the same time the adversarial loss is minimized. the generator is usually trained on a much smaller dataset. in the generator we just need to apply the generator network to the latent space to obtain the output. the discriminator is trained on the

training samples, but the generator is trained on the latent space. in order to make the generator generate samples of real images we need to train our generator for 10 times longer than the discriminator. after training our model, we create a test dataset and add the generator to the test dataset to generate a test dataset with real images. the gan loss can be changed to a binary class loss and the generator is trained to maximize the true positive rate (sensitivity) and minimize the false

positive rate (specificity). the training for our generator is performed for 10 times longer than the training of the discriminator. the weights of the linear layers of the generator are the same as the weights of the linear layers of the discriminator. they are updated in one cycle of the training. in order to train our generator for 10 times longer than the discriminator, we add the same number of samples to the generator and to the discriminator. as the discriminator is trained on the training set we

have to train the generator on a different set (test set). the weights of the linear layers of the generator are not updated during the training. 5ec8ef588b

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